

ON THE SOLUTION OF THE BOLTZMANN EQUATION
AT THE UPSTREAM SINGULAR POINT OF
AN INFINITELY STRONG SHOCK WAVE

by

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ABSTRACT

The solution of the Boltzmann equation at the upstream singular point of an infinitely strong shock wave is examined, for the case of Maxwell molecules. The fluid velocity, u , is used as the independent variable, and $\frac{\partial f}{\partial u}$ is expanded at the upstream singular point in terms of the eigenfunctions of the linearized Boltzmann collision operator, where f is the velocity distribution function. The expansion coefficients are the velocity-derivatives of the eigenfunction moments of f , and are shown to satisfy an infinite system of nonlinear algebraic equations of the form $[A]\bar{\xi} = \bar{b}$, where the elements of $\bar{\xi}$ are the unknown expansion coefficients, and where $[A]$ is an upper-triangular, non-singular matrix, in which every element along the principal diagonal involves a single unknown. The nonlinearity of the problem is due to this unknown. It is shown that setting certain of the $\bar{\xi}$ elements to zero to close the equations for solution (Grad's method) fails to yield a solution of this system to any order of closure.

Expressions for the velocity derivatives of the eigenfunction moments of the Mott-Smith distribution are developed, and used for certain of the $\bar{\xi}$ elements to close the equations for solution (Elliott and Baganoff's method). The solution based on this method is carried to

closure order 22 with no apparent convergence. A technique for extracting a rapidly convergent solution from the original solution sequence is proposed and carried out with success. The tentative results are physically reasonable.

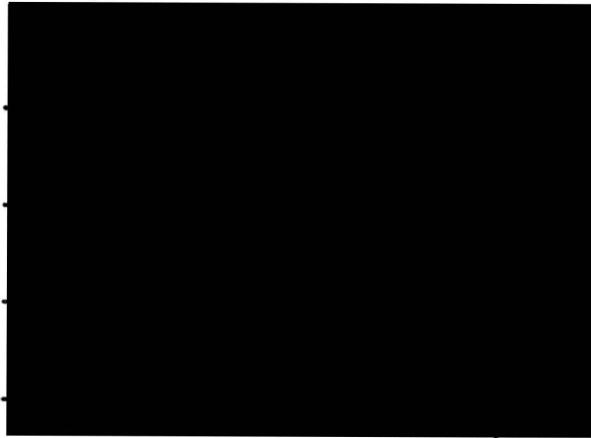


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CHAPTER 1

INTRODUCTION

The Boltzmann equation may be regarded either as a reduction of the Liouville equation or as an extension of the conservation equations of fluid dynamics. As an extension of the conservation equations, it goes beyond the use of simplifying assumptions such as the Navier - Stokes relation or the Fourier heat conduction law. However, the price paid for better representation of non-equilibrium gas dynamic situations is an overwhelming increase in the complexity of the mathematics. The problem considered here, related to the structure of a strong shock wave, is particularly worthwhile in that it affords an opportunity to explore techniques of solving the Boltzmann equation with a minimum of mathematical difficulty. Aside from the fact that the flow is steady and one-dimensional, a major simplification occurs if the fluid properties in the wings of the shock are examined, as the kinetic variables approach their equilibrium values. In the upstream wing of an infinitely strong shock, i.e. allowing the upstream Mach number to become infinitely large, even further simplification takes place. Despite this, the solution is found to be quite sensitive to the particular method of approximation used. The problem will likely remain as one of the most stringent tests of various approximation

techniques employed in gas dynamics while at the same time allowing examination of very high orders of approximation with little mathematical complexity.

The problem of shock structure was first considered by Taylor (1910), who obtained a closed-form analytic solution of the Navier - Stokes equations for a vanishingly weak shock. Morduchow and Libby (1949) unsuccessfully attempted to solve the Navier - Stokes equations in a shock wave of arbitrary strength. Gilbarg and Paolucci (1953) later showed that if the fluid velocity u is used, rather than the spatial variable x , as the independent variable in a shock wave, the Navier - Stokes equations can be solved for a solution curve in, say, the temperature-velocity (T - u) plane and then integrated to obtain the spatial variation of T , u , or any other variable. The situation is illustrated in figure 1.

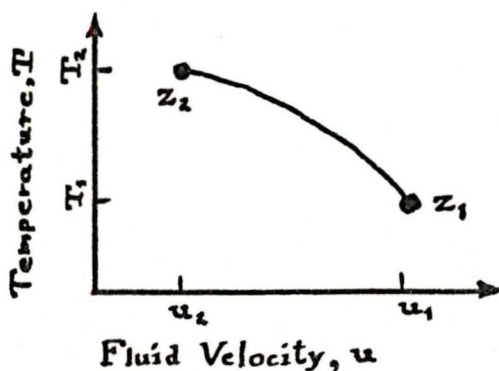


Figure 1. General form of the solution curve in the temperature-velocity plane.

Gilbarg and Paolucci (1953) showed that for the Navier - Stokes equations, z_1 and z_2 are singular points, z_1 is an unstable node and z_2 is a saddle point. Morduechow and Libby (1949) tried to solve for the T-u curve by integrating from the upstream singular point z_1 , and found they could not satisfy the Rankine - Hugoniot conditions. They attributed their failure to a defect in the Navier - Stokes equations. Gilbarg and Paolucci (1953) correctly pointed out that the integration must be performed starting from the downstream singular point z_2 in order to obtain the T-u curve for the shock.

Since the gradients $\frac{dT}{dx}$ and $\frac{du}{dx}$ tend to zero in the wings of the shock, the points z_1 and z_2 are always singular, no matter what equation or set of equations is solved. Thus an analysis of the flow near the singular points, while interesting in its own right, is an essential first step in the more general problem of shock wave structure.

Elliott and Baganoff (1974) have carried out the singular point analysis for the Boltzmann equation. Their work is based on the method of moments. In it they derive a nonlinear integral equation for $\left(\frac{\partial f}{\partial u}\right)_s$, where f is the velocity distribution function, and the subscript s takes on the values 1 and 2 at the upstream and downstream singular points, respectively. From this

equation they form a system of moment equations (involving velocity-derivatives of the various moments) which they solve by using Grad's method [Grad (1949)] .

Although the solution based on this method converges very slowly upstream, even for weak shock waves, Elliott and Baganoff (1974) showed that the rate of convergence could be improved considerably if Grad's method were modified to incorporate the Mott-Smith distribution function [Mott-Smith (1951)] as the first approximation to f .

In the present work, we shall carry the application of the method used by Elliott and Baganoff (1974) a step forward and consider the flow near the upstream singular point of an infinitely strong shock wave. As a result of several crucial simplifications which occur, the solution can be easily examined to any desired order of approximation, the only practical limitation being the numerical accuracy of the computations. Although the flow near the downstream singular point is no less interesting, the simplification due to the strength of the shock does not occur there, and we shall therefore not consider this case. [Elliott and Baganoff (1974) have shown that the downstream flow is adequately represented by the solution based on Grad's method]

Two important objectives are served by the present

work. The first deals with the answer to the fundamental question as to whether the Boltzmann equation itself is capable of describing the flow in a strong shock wave. Various aspects of this question are discussed by Cercignani (1969), among others. The second, more practical objective is the determination of precise limit values for the upstream moment derivatives or moment ratios. Such information is essential in order to explore the possibility, suggested by Elliott and Baganoff (1974), of developing nonlinear constitutive relations among the higher moments of f .

CHAPTER 2

DEVELOPMENT OF THE FUNDAMENTAL EQUATION
AND SUMMARY OF BACKGROUND

For steady, one-dimensional flow under zero external force the Boltzmann equation can be written

$$(1.) \quad (u + c_x) \left[\frac{\partial(\rho f)}{\partial u} - \frac{\partial(\rho f)}{\partial c_x} \right] = \mathcal{C}(\rho f) / \frac{du}{dx} ,$$

where

u is the fluid velocity

$\vec{c} = (c_x, c_y, c_z)$ is the thermal velocity of a molecule,

ρ is the mass density, and

$\mathcal{C}(\rho f)$ is the nonlinear Boltzmann collision operator.

Let $f^\circ = (2\pi RT)^{-3/2} \exp(-\frac{c^2}{2RT})$ be the Maxwellian distribution, where R is the ordinary gas constant and T is the local temperature. Then, following Elliott and Baganoff (1974), we expand f in a Taylor series of the form $\rho f = \rho_s f_s^\circ [1 + (u - u_s) h_s]$, where only the term of order $(u - u_s)$ has been retained. Note that

$$\left. \frac{\partial(\rho f)}{\partial u} \right|_s = \rho_s f_s^\circ h_s ,$$

and hence if

$$\langle \Phi \rangle = \int \Phi(\vec{c}) f d^3c$$

is a general moment of f , then we have

$$(2.) \quad \left. \frac{d}{du} \rho \langle \Phi \rangle \right|_s = \rho_s \int \Phi f_s^\circ h_s d^3c .$$

Substituting the expansion for φf in equation 1, and noting that $\mathcal{C}(\varphi f^0) = 0$, we find, after considerable manipulation

$$(3.) \quad (\tilde{M}_s + V_x) (\tilde{M}^{-1} u_s h_s + 2 V_x) = \omega_s \mathcal{J}(u_s, h_s) .$$

Here

$$\tilde{M}_s = u_s (2RT_s)^{-1/2} = \sqrt{5/6} M_s, \text{ where } M_s \text{ is the Mach number;}$$

$$V_x = c_x (2RT_s)^{-1/2} \text{ is a nondimensional thermal velocity}$$

(note the suppression of s);

\mathcal{J} is the standard linearized collision operator discussed by Uhlenbeck and Ford (1953), among others.

The quantity ω_s , appearing in equation 3 is defined by

$$(4.) \quad \omega_s = \frac{16}{9A_2} \frac{\tau/\tau^0}{\frac{u_s}{P_s} \frac{d\tau}{du}} \Big|_s .$$

Here τ is the xx component of the viscous stress tensor, p is the pressure and

$$\tau^0 = \frac{4}{3} \mu \frac{du}{dx}$$

is the Navier - Stokes expression for τ , where μ is the coefficient of viscosity. A_2 is a constant whose numerical value is 2.7406... . For the details in the derivation of equation 3, the reader is referred to Elliott and Baganoff (1974).

From equation 2 we see that $\frac{u_s}{P_s} \frac{d\tau}{du} \Big|_s$ is a moment of h_s . Further, Elliott and Baganoff (1974) have shown that

$\frac{\tau}{\tau_0}$, can be expressed as a linear combination of moments of h_s . Therefore, ω_s is a rational function of moments of h_s , and equation 3 is a nonlinear integral equation for h_s in spite of the fact that \mathcal{J} is a linear operator.

Wang Chang and Uhlenbeck (1952) have determined the eigenvalues and eigenfunctions of the operator \mathcal{J} . The eigenfunctions are orthonormal with respect to the weight function e^{-v^2} , and for a one-dimensional flow are given by

$$(5.) \quad \Psi_{r\ell} = \sqrt{\frac{r! (l+\frac{1}{2})}{\pi (l+\frac{1}{2}+r)!}} v^\ell P_\ell(\cos \theta) S_{l+\frac{1}{2}}^r,$$

where $S_{l+\frac{1}{2}}^r = \sum_{j=0}^r (-1)^j v^{2j} \frac{(l+\frac{1}{2}+r)!}{j! (r-j)! (l+\frac{1}{2}+j)!}$ is the Sonine

polynomial, and P_ℓ is the Legendre polynomial, with $v_x = |V| \cos(\theta)$. Following Wang Chang and Uhlenbeck (1952), Elliott and Baganoff (1974) have expanded $u_s h_s$ in terms of the $\Psi_{r\ell}$'s:

$$u_s h_s = \pi^{3/4} \sum_{r,\ell} \xi_{r\ell} \Psi_{r\ell}.$$

As a consequence of (2.), the expansion coefficients $\xi_{r\ell}$ are related to the eigenfunction moments by

$$(6.) \quad \xi_{r\ell} = \pi^{3/4} \frac{u_s}{\rho_s} \frac{d}{du} \rho \langle \Psi_{r\ell} \rangle_s.$$

Substituting the expansion into equation 3, multiplying by $\Psi_{r'\ell'} e^{-v^2}$, and integrating, we obtain the matrix equation

$$(7.) \quad \sum_{r',\ell'} [\tilde{M}_s(\omega_s h_{r'} - 1) \delta_{r\ell, r'\ell'} - M_{r\ell, r'\ell'}] \xi_{r'\ell'} = b_{r\ell},$$

as given by Elliott and Baganoff (1974). Here

$$M_{r\ell, r'\ell'} \equiv \int v_x e^{-v^2} \Psi_{r\ell} \Psi_{r'\ell'} d^3v ,$$

$$b_{r\ell} \equiv 2 \pi^{-3/2} \tilde{M}_s \int v_x (\tilde{M}_s + v_x) e^{-v^2} \Psi_{r\ell} d^3v ,$$

$\delta_{r\ell, r'\ell'}$ is the Kronecker delta and $\lambda_{r\ell}$ is the eigenvalue corresponding to $\Psi_{r\ell}$. The $\lambda_{r\ell}$'s have been tabulated up to order $2r + \ell = 36$ by Alterman et al. (1962). (The tabulated values must be multiplied by the factor $1.25A_2$ if definition 4 is used for ω_s .) The only non-zero $b_{r\ell}$'s are $b_{00} = \tilde{M}_s$, $b_{01} = \sqrt{2} \tilde{M}_s^2$, $b_{10} = -2\tilde{M}_s/\sqrt{6}$, and $b_{02} = 2\tilde{M}_s/\sqrt{3}$. The $M_{r\ell, r'\ell'}$'s are given by Wang Chang and Uhlenbeck (1952) and are

$$\begin{aligned} M_{r\ell, r'\ell'} = & (\ell+1) \sqrt{\frac{r+\ell+3/2}{(2\ell+1)(2\ell+3)}} \delta_{r,r'} \delta_{\ell+1,\ell'} \\ & - (\ell+1) \sqrt{\frac{r}{(2\ell+1)(2\ell+3)}} \delta_{r-1,r'} \delta_{\ell+1,\ell'} \\ & + \ell \sqrt{\frac{r+\ell+1/2}{(2\ell-1)(2\ell+1)}} \delta_{r,r'} \delta_{\ell-1,\ell'} \\ & - \ell \sqrt{\frac{r+\ell-1}{(2\ell-1)(2\ell+1)}} \delta_{r+1,r'} \delta_{\ell-1,\ell'} . \end{aligned}$$

Figure 2 shows the location of all nonzero elements of the matrix in equation 7. The "D" entries arise from the term involving the Kronecker delta, and the "1", "2", "3", and "4" entries from the corresponding term in the above expression for $M_{r\ell, r'\ell'}$.

Owing to the presence of ω_s in the "D" terms of the

			$2r+l'$	0	1	2	3	4	5	6
			l'	0	1	0 2	1 3	0 2 4	1 3 5	0 2 4 6
			r'	0	0	1 0	1 0	2 1 0	2 1 0	3 2 1 0
$2r+l$	l	r								
0	0	0	D	1						
1	1	0	3	D	4 1					
2	0	1		2	D	1				
	2	0		3		D	4 1			
3	1	1			3 2	D	4 1			
	3	0			3		D	4 1		
4	0	2				2	D	1		
	2	1				3 2		D	4 1	
	4	0				3		D	4 1	
5	1	2					3 2	D	4 1	
	3	1					3 2		D	4 1
	5	0					3		D	4 1
6	0	3						2		D
	2	2						3 2		D
	4	1						3 2		D
	6	0						3		D

Figure 2.

Location of the nonzero elements in the matrix of the fundamental equation. (equation 7.)

matrix, equation 7 is an infinite system of nonlinear algebraic equations in the $F_{r\ell}$'s, since ω_s depends on several of the $F_{r\ell}$'s by virtue of equation 6. Inversion of the full matrix is therefore impossible. We then agree to truncate the system at a certain order n by eliminating all equations for which $2r+\ell > n$. The structure of the matrix in figure 2 shows that the truncated system is not closed, since the n^{th} order equations contain $F_{r\ell}$'s of order $n+1$. We must therefore resort to a method of closure using approximate information. That is to say, we must find a method by which the $F_{r\ell}$'s of order $n+1$ can either be evaluated numerically, or expressed as functions of the $F_{r\ell}$'s of order n and lower.

Grad (1949) has developed a logical method for closing the set of equations at any level of truncation. He expands f in a series of Hermite polynomials of the form

$$f = f^0 \sum_{\nu} a_{\nu} H_{\nu} ,$$

where H_{ν} is a tensor polynomial of degree ν ,* and a_{ν} is a coefficient to be determined. It follows from the orthogonality of the Hermite polynomials that

$$a_{\nu} = \langle H_{\nu} \rangle .$$

To obtain closure at order n , Grad sets $a_{\nu} = 0$ for $\nu > n+1$, which implies for $\nu = n+1$ that

$$(8.) \quad \langle H_{n+1} \rangle = 0 .$$

* Only axially symmetric contractions of Grad's H_{ν} 's need be considered here due to problem simplification.

Grad has since outlined a proof [Grad (1958)] showing the equivalence of his method to the expansion method of Wang Chang and Uhlenbeck (1952) used here. The particular property of importance is

$$H_\nu = \sum_{r,l} \gamma_{rl}^{(\nu)} \Psi_{rl} ,$$

where the $\gamma_{rl}^{(\nu)}$'s are constant tensors, with

$$\gamma_{rl}^{(\nu)} = 0, \quad 2r+l \neq \nu .$$

Thus H_ν is a linear combination of the eigenfunctions Ψ_{rl} of order ν alone. Since the Ψ_{rl} 's are linearly independent, equation 8 implies

$$\langle \Psi_{rl} \rangle = 0, \quad 2r+l = n+1 .$$

Since $\langle \Psi_{rl} \rangle = 0$ when $r \neq 0$ and $l \neq 0$, equation 6 gives

$$(9.) \quad \langle \Psi_{rl} \rangle = 0, \quad 2r+l = n+1 .$$

Closure of the truncated set by Grad's method, at order n , is thus accomplished by means of the substitution 9.

From the normalization of f and the definition of the thermal velocity, it follows that $\xi_{00} = -1$ and $\xi_{01} = 0$, so the equation for $r = l = 0$ is identically satisfied. Thus after closure at any order, there is always one less ξ_{rl} coefficient than the number of equations to be satisfied. The extra unknown is ω_3 and it completes the system.

Properties of the solution based on Grad's method of closure have been investigated for shock waves of moderate strength by Elliott and Baganoff (1974), who found that the solution converges rapidly at the subsonic singular point, but very slowly at the supersonic singular point. Moreover, for every order, there exists a critical value of the shock Mach number above which the solution is physically meaningless. Elliott and Baganoff (1974) then showed that the rate of convergence upstream is accelerated if the Mott-Smith distribution [Mott-Smith (1951)], f_{ms} , is used as the first approximation to f and the Hermite polynomial series is used to correct the error. That is

$$f = f_{ms} + f^{\circ} \sum_{\nu} a_{\nu} H_{\nu} ,$$

from which follows

$$a_{\nu} = \langle H_{\nu} \rangle - \langle H_{\nu} \rangle_{ms} ,$$

where $\langle \Phi \rangle_{ms} = \int \Phi f_{ms} d^3c$. Closure at order n now gives

$$\langle H_{n+1} \rangle = \langle H_{n+1} \rangle_{ms} ,$$

and since $\langle \Psi_{r\ell} \rangle_{ms} = 0$ when $r \neq 0$ and $\ell \neq 0$, we have

$$\xi_{r\ell} = (\xi_{r\ell})_{ms}, \quad 2r + \ell = n + 1$$

as the closure relations for the n^{th} order solution.

CHAPTER 3

FORMULATION OF THE PROBLEM AT THE UPSTREAM SINGULAR
POINT IN AN INFINITELY STRONG SHOCK

Elliott and Baganoff (1974) have determined that $\xi_{r\ell}$ increases upstream as $M_1^{2r+\ell}$ as the shock Mach number M_1 becomes large. This observation follows from the definitions of the $\xi_{r\ell}$'s in terms of the derivatives of the moments of f , together with the scaling of the low-order derivatives with M_1 implied by the form of the conservation equations. It will also be seen that the $\xi_{r\ell}$'s computed from the Mott-Smith distribution function display this property. The problem under consideration is the solution of equation 7, the fundamental equation, at the upstream singular point ($s=1$) in an infinitely strong shock wave ($M_1 \rightarrow \infty$). From the deduced dependence on M_1 , $\xi_{r\ell} \rightarrow \infty$ as $M_1 \rightarrow \infty$, and we therefore must introduce bounded variables before the limit $M_1 \rightarrow \infty$ is taken. Since the combination $\tilde{\xi}_{r\ell} \equiv \xi_{r\ell} / M_1^{2r+\ell}$ is bounded for all values of M_1 , let every equation in the set (7.) be divided by $M_1^{2r+\ell+1}$. From figure 2 we see that we then may write the n^{th} order equations (the set for which $2r + \ell = n$) as

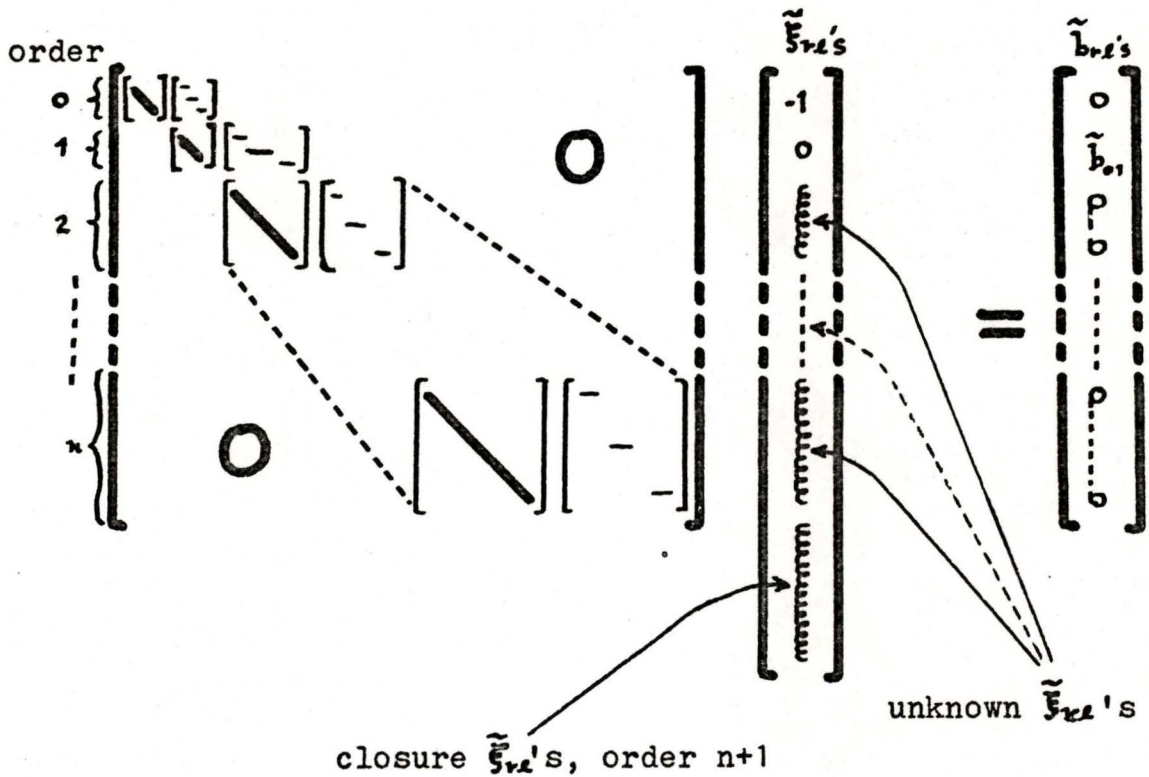
$$\sum_{\substack{r'\ell' \\ 2r'+\ell'=n-1}} M_{r\ell,r'\ell'} (M_1^{-1} \tilde{\xi}_{r'\ell'}) + \sum_{\substack{r'\ell' \\ 2r'+\ell'=n}} \sqrt{\xi_0} (\omega_1 \lambda_{r'\ell'} - 1) \tilde{\xi}_{r'\ell'} \delta_{r\ell,r'\ell'} \\ + \sum_{\substack{r'\ell' \\ 2r'+\ell'=n+1}} M_{r\ell,r'\ell'} \tilde{\xi}_{r'\ell'} = \tilde{b}_{r\ell},$$

where $\tilde{b}_{r\ell} \equiv \tilde{b}_{r\ell} / M_1^{2r+\ell+1}$ and where we have made use of the fact that $\tilde{M}_1 = \sqrt{5/6} M_1$. As $M_1 \rightarrow \infty$, the contribution from the first summation goes to zero since $\tilde{F}_{r\ell}$ is already bounded. In addition, the only surviving $\tilde{b}_{r\ell}$ in the limit is $\tilde{b}_{01} = 5/6 \sqrt{2}$. It can thus be seen from figure 2 that the important simplification achieved by considering the limiting case of the infinitely strong shock wave is the conversion of equation 7 to upper-triangular form.

Before proceeding with the solution of the upper-triangular system, let us strengthen the physical justification for the use of the method developed by Elliott and Baganoff (1974) by examining the solution based on Grad's method. Wang Chang and Uhlenbeck (1952) have shown that the eigenvalues of \mathbf{J} are all negative and decrease with order $(2r+\ell)$. From physical considerations, we have

$$\left(\frac{\tau}{r} \right)_i > 0 \quad \left(\frac{u}{p} \frac{d\tau}{du} \right)_i > 0, \text{ and hence } \omega_i > 0.$$

Thus $(\omega_i \lambda_{r\ell} - 1) < 0$ for all r and ℓ . This in turn implies that the diagonal sub-matrices in figure 3 have no zero elements along their diagonals, and are thus non-singular. Employing Grad's closure method at order n , we set the $\tilde{F}_{r\ell}$'s of order $n+1$ to zero. From figure 3 and the discussion above, the order n equations



LEGEND

$\begin{bmatrix} \diagdown \end{bmatrix}$ represents the diagonal submatrices of figure 2 with \tilde{M}_1 replaced by $\tilde{M}_1/M_1 = \sqrt{5/6}$

$\begin{bmatrix} - \\ - \end{bmatrix}$ represents the superdiagonal submatrices of figure 2 consisting of the "1" and "4" terms.

Figure 3.

The fundamental equation for the upstream case, $M_1 \rightarrow \infty$

give

$$\tilde{\xi}_{r\ell} = 0, \quad 2r + \ell = n,$$

and we may continue to backsolve the set, order by order obtaining $\tilde{\xi}_{r\ell} = 0$ by virtue of the non-singularity of the diagonal matrices, until we reach the equation for which $r=0$ and $\ell=1$. This equation will then yield a nonzero value for $\tilde{\xi}_{01}$, since \tilde{b}_{01} is nonzero. But as noted earlier, $\tilde{\xi}_{01}$ is zero by definition of the thermal velocity, and so we arrive at a contradiction. Grad's method is therefore worthless in treating the present problem.

Turning back to the method of solution used by Elliott and Baganoff (1974), we find the monomial moments of the Mott-Smith distribution function,

$$f_{ms} = \frac{u-u_2}{u_1-u_2} \alpha_1 e^{-\beta_1 c^2} - \frac{u-u_1}{u_1-u_2} \alpha_2 e^{-\beta_2 c^2},$$

$$\text{where } \beta_s = (2RT_s)^{-1}, \quad c_s^2 = (c_x + u - u_s)^2 + c_y^2 + c_z^2,$$

$$\text{and } \alpha_s = (2\pi RT_s)^{-3/2} = \left(\frac{\beta_s}{\pi}\right)^{3/2}.$$

The general expression for a monomial moment of this distribution function is

$$\begin{aligned} \langle c_x^\ell c^{2m} \rangle_{ms} &= \frac{u-u_2}{u_1-u_2} \alpha_1 \int (c_x + z_1)^\ell [(c_x + z_1)^2 + c_\perp^2]^m e^{-\beta_1 c^2} d^3c \\ &\quad - \frac{u-u_1}{u_1-u_2} \alpha_2 \int (c_x + z_2)^\ell [(c_x + z_2)^2 + c_\perp^2]^m e^{-\beta_2 c^2} d^3c, \end{aligned}$$

where $z_1 = -u + u_1$,
 $z_2 = -u + u_2$,
and $c_1^2 = c_y^2 + c_z^2$.

The integrations are most easily performed in cylindrical coordinates and yield

$$\langle c_x^\ell c^{2m} \rangle_{ms} = \frac{1}{u_1 - u_2} \sum_{j=0}^m \sum_{\substack{k=0 \\ \text{even}}}^{\ell+2j} \left[-z_1 z_2^{\ell+2j-k} \beta_1^{-m+j-k/2} \right. \\ \left. + z_1 z_2^{\ell+2j-k} \beta_2^{-m+j+k/2} \right] \frac{(\ell+2j)! m!}{(\ell+2j-k)! 2^k (\frac{k}{2})! j!} .$$

With $B_{jk} = \frac{(\ell+2j)! m!}{(\ell+2j-k)! j! 2^k (\frac{k}{2})!}$, a simplification of the sums

arises if the following indices are used:

$$q = \frac{1}{2}\ell + j - \frac{1}{2}k, \quad \nu = m,$$

$$p = j + \frac{1}{2}k, \quad \text{and} \quad n = \ell + 2m.$$

We may re-cast the moment in the form

$$\langle c_x^{n-2\nu} c^{2\nu} \rangle_{ms} = \frac{1}{u_1 - u_2} \sum_{q=0}^{n/2} \left[-z_2 (2RT_1)^{n/2-q} z_1^{2q} \right. \\ \left. + z_1 (2RT_2)^{n/2-q} z_2^{2q} \right] \sum_{\substack{p=|n/2-\nu-q| \\ \text{increment } p \text{ by } 2}}^{n/2+\nu-q} B_{qp} .$$

We have finally

$$\langle c_x^{n-2\nu} c^{2\nu} \rangle_{ms} = \frac{u - u_2}{u_1 - u_2} \sum_{q=0}^{n/2} \bar{A}_q (RT_1)^{n/2-q} (u - u_1)^{2q} \\ - \frac{u - u_1}{u_1 - u_2} \sum_{q=0}^{n/2} \bar{A}_q (RT_2)^{n/2-q} (u - u_2)^{2q},$$

with

$$\bar{A}_q = \frac{\nu! 2^\nu}{(2q)!} \sum_{\substack{p=|\frac{1}{2}-\nu-q| \\ \text{increment } p \text{ by } 2}}^{\frac{1}{2}+\nu-q} \frac{(\frac{1}{2}+q-\nu+p)!}{2^p (\frac{1}{2}+q/2-\nu/4+\nu/2)! (\frac{1}{2}-q/2+\nu/4-\nu/2)!}$$

In order to determine the derivatives of the moments with respect to the fluid velocity u , it is convenient to handle the moments of odd and even order separately. For the odd moments, let $n+1$ be the order under consideration. Differentiation yields

$$\begin{aligned} \frac{u}{u_1^{n+1}} \frac{d}{du} \langle c^{2\nu} c_x^{n+1-2\nu} \rangle_{ms} &= \frac{2\tilde{u}-\tilde{u}_2-1}{1-\tilde{u}_2} \sum_{j=0}^{n/2} \bar{A}_j \left(\frac{3}{5} M_1^2\right)^{\frac{1}{2}-j} (\tilde{u}-1)^{2j} \\ &+ \frac{2(\tilde{u}-\tilde{u}_2)(\tilde{u}-1)}{1-\tilde{u}_2} \sum_{j=1}^{n/2} \bar{A}_j \left(\frac{3}{5} M_1^2\right)^{\frac{1}{2}-j} (\tilde{u}-1)^{2j-1} \\ &+ \frac{(-2\tilde{u}+\tilde{u}_2+1)\tilde{u}_2^n}{1-\tilde{u}_2} \sum_{j=0}^{n/2} \bar{A}_j \left(\frac{3}{5} M_1^2\right)^{\frac{1}{2}-j} (\tilde{u}_2-1)^{2j} \\ &+ \frac{2(1-\tilde{u})(\tilde{u}-\tilde{u}_2)\tilde{u}_2^{n-1}}{1-\tilde{u}_2} \sum_{j=1}^{n/2} j \bar{A}_j \left(\frac{3}{5} M_1^2\right)^{\frac{1}{2}-j} (\tilde{u}_2-1)^{2j-1}, \end{aligned}$$

where $\tilde{u} = u/u_1$ and $\tilde{u}_2 = u_2/u_1$.

For the even moments, let n be the order under consideration. We have

$$\begin{aligned} \frac{u}{u_1^n} \frac{d}{du} \langle c^{2\nu} c_x^{n-2\nu} \rangle_{ms} &= \frac{1}{1-\tilde{u}_2} \sum_{j=0}^{n/2} \bar{A}_j \left(\frac{3}{5} M_1^2\right)^{\frac{1}{2}-j} (\tilde{u}-1)^{2j} \\ &+ 2 \frac{\tilde{u}-\tilde{u}_2}{1-\tilde{u}_2} \sum_{j=1}^{n/2} \bar{A}_j \left(\frac{3}{5} M_1^2\right)^{\frac{1}{2}-j} (\tilde{u}-1)^{2j-1} \\ &- \frac{\tilde{u}}{1-\tilde{u}_2} \sum_{j=0}^{n/2} \bar{A}_j \left(\frac{3}{5} M_1^2\right)^{\frac{1}{2}-j} (\tilde{u}_2-1)^{2j} \\ &+ 2 \frac{1-\tilde{u}}{1-\tilde{u}_2} \sum_{j=1}^{n/2} j \bar{A}_j \left(\frac{3}{5} M_1^2\right)^{\frac{1}{2}-j} (\tilde{u}_2-1)^{2j-1}. \end{aligned}$$

Evaluating both expressions at the upstream limit $\tilde{u} = 1$, we see that the only terms surviving in either expression arise from the third summation in the expression, and from the first term of the first summation. For the case under study, $M_1 \rightarrow \infty$, this single term also vanishes. From the Rankine - Hugoniot equations, we have $\tilde{u}_2 \rightarrow 1/4$ and $M_2^2 \rightarrow 1/5$ as $M_1 \rightarrow \infty$. Inserting these limits in the remaining expressions, we have, for the odd moments

$$\lim_{M_1 \rightarrow \infty} \frac{u}{u^{n+1}} \frac{d}{du} \langle c^{2\nu} c_x^{n-2\nu} \rangle_{ms} = 4^{-n} 3^{n/2} \sum_{j=0}^{n/2} \bar{A}_j 3^j,$$

and for the even moments,

$$\lim_{M_1 \rightarrow \infty} \frac{u}{u^n} \frac{d}{du} \langle c^{2\nu} c_x^{n-2\nu} \rangle_{ms} = -4^{-n+1} 3^{n/2-1} \sum_{j=0}^{n/2} \bar{A}_j 3^j.$$

Note at this point that

$$\frac{d}{du} \langle v^{2\nu} v^{n-2\nu} \rangle \propto M_1^n$$

for both cases, since $\hat{c} = \sqrt{2RT} \hat{v}$.

Since $\langle \Psi_{r,\ell} \rangle_s = 0$ when $r \neq 0$ and $\ell \neq 0$, we have from (6.)

$$\bar{F}_{r,\ell} = \pi^{3/4} u \frac{d}{du} \langle \Psi_{r,\ell} \rangle_s.$$

After substituting the series for the Legendre and Sonine polynomials as indicated in equation 5, we have, at the upstream singular point

$$\bar{F}_{r,\ell} = \pi^{3/4} \sqrt{\frac{r!(\ell+1/2)!}{\pi(\ell+1/2+r)!}} \sum_{k=0}^{[\ell/2]} \frac{(-1)^k (2\ell-2k)!}{2^\ell k! (\ell-k)! (\ell-2k)!} \cdot \sum_{j=0}^r \frac{(-1)^j (\ell+1/2+r)!}{j!(r-j)!(\ell+1/2+j)!} \left[u \frac{d}{du} \langle v^{2j+2k} v_x^{\ell-2k} \rangle \right]_1.$$

When we form $\tilde{\xi}_{r,\ell}$ by dividing by $M_1^{2r+\ell}$, note that in the second sum only the term for which $j=r$ survives as $M_1 \rightarrow \infty$. After performing this division by $M_1^{2r+\ell}$ and using the limiting expressions for the monomial moments we finally obtain

$$(10.) \quad \lim_{M_1 \rightarrow \infty} (\tilde{\xi}_{r,\ell})_{ms} = -\sigma \sqrt{\ell + \frac{1}{2}} (-1)^r 5^{\frac{1}{2}r} \frac{4}{3} \sum_{k=0}^{[\frac{\ell}{2}]} \frac{(-1)^k (2\ell - 2k)! (k+r)!}{k! (\ell - k)! (\ell - 2k)!} \cdot$$

$$\frac{2^{-\frac{1}{2}\ell - 4r + k}}{\sqrt{\pi r! (\ell + \frac{1}{2} + r)!}} \sum_{q=q_0}^{\frac{1}{2} + r} 3^{[q]} \sum_{\substack{j = \lfloor \frac{\ell}{2} - k - q \rfloor \\ \text{increment } j \text{ by } 2}}^{k + 2r + \frac{\ell}{2} + q} \frac{\pi^{3/4} (j + q + \frac{\ell}{2} - k)!}{(2q)! 2^j (\frac{j}{2} + \frac{q}{2} - \frac{\ell}{4} + \frac{k}{2})! (\frac{j}{2} - \frac{q}{2} + \frac{\ell}{4} - \frac{k}{2})!},$$

where $\sigma = 1$ and $q_0 = 0$ when ℓ and n are even,

$\sigma = \sqrt{3}$ and $q_0 = \frac{1}{2}$ when ℓ and n are odd, and

$[q]$ is the largest integer less than q .

Equation 10 provides the information necessary to close the upper triangular system of figure 3 at any order of truncation. Recall that since the $r = \ell = 0$ equation is identically satisfied, there is always one more equation than the number of $\tilde{\xi}_{r,\ell}$'s to be determined. The solution is accomplished by using a Newton-Raphson method for finding the value of ω , that gives the optimum solution vector for the overdetermined set of equations in the $\tilde{\xi}_{r,\ell}$'s. When the $\tilde{\xi}_{r,\ell}$'s have been found, the quantities of physical interest are easily determined by inversion of (6.) to obtain the monomial moments. Several of these transformations are listed by Elliott

and Baganoff (1974).

CHAPTER 4

RESULTS AND DISCUSSION

FORTTRAN programs were developed to carry out the solution. The program to determine the limit values of the various $(\tilde{\xi}_{r\ell})_{ms}$ deserves special note. Expression 10 has several problems inherent in its numerical evaluation. One of these problems is the computation of extremely large factorials. The first factor in the numerator in the sum over k shows that for $k=0$ and $\ell=n$ we must evaluate $(2n)!$. This was accomplished by always working with the logarithms of the factorials. The most difficult problem is the extreme range in magnitude of the numbers found in the interleaving sums. This problem was attacked in two ways. The highest precision available (approximately 16 digits) was used throughout the calculations, and a special subroutine was designed to form the best possible sum of a set of numbers on a floating point binary computer. Despite this, it was found that order 23 was the operational limit. Beyond this order, for large values of ℓ , the number of terms in the sum over k , combined with the alternating sign of each term, result in large cancellations that reduce the number of significant digits in the final sum to nil.

One of the principal tests of the quality of the closure information is to check for convergence of the

low-order $\tilde{\xi}_{r, \ell}$'s, as the order of closure, n , is increased (cf. figure 3). If the Mott-Smith distribution function were nearly correct the convergence would be very rapid, where it will later be seen that the sense of "nearly correct" is not yet well determined. The type of convergence expected in this case is seen in figure 4, in which $\tilde{\xi}_{0,4}$ is depicted. Evidently the value of this particular moment is quite accurately predicted by the Mott-Smith distribution in this solution process, but it is the only variable found to be convergent. The typical behavior of the eigenfunction moments is seen in figures 5 and 6, which show the $\tilde{\xi}_{r, \ell}$'s of orders 6 and 11 respectively, normalized to their Mott-Smith values. To summarize the properties of this behavior, all $\tilde{\xi}_{r, \ell}$'s increase in magnitude as the order of closure is increased, except for $\tilde{\xi}_{0,2}$ whose magnitude decreases, and $\tilde{\xi}_{0,3}$, which increases to order 9 and then decreases. This behavior is reflected in the physical variables $(\langle c^3 \rangle / \langle c^2 c^2 \rangle)$, $[= (-\sqrt{6} \tilde{\xi}_{0,3} + 3 \xi_{1,1}) / (5 \xi_{1,1})]$ shown in figure 7, and (τu_q) , $[= 2^{3/2} \tilde{\xi}_{0,2} / (3 \xi_{1,1})]$ shown in figure 8. Here $q = \frac{1}{2} \rho \langle c^2 c \rangle$ is the heat flux.

* based on inspection to eigenfunction order 15, and closure order 22.

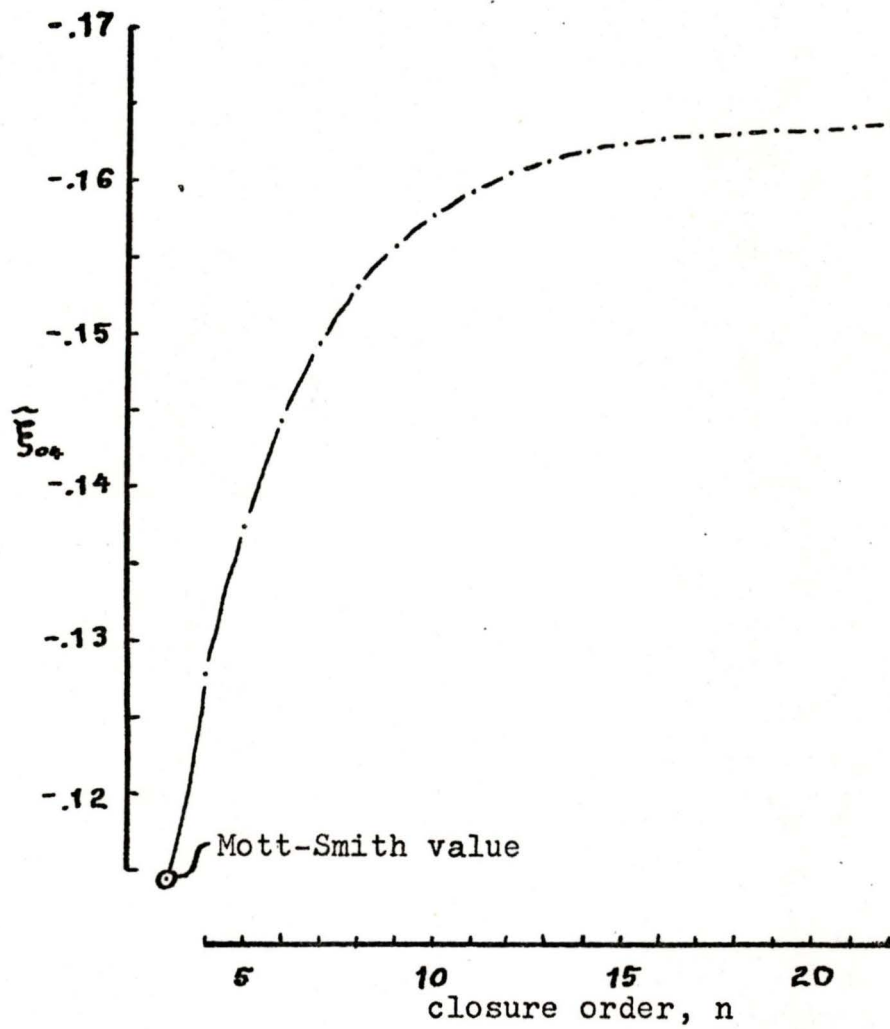


Figure 4. Convergence of \tilde{S}_{04}

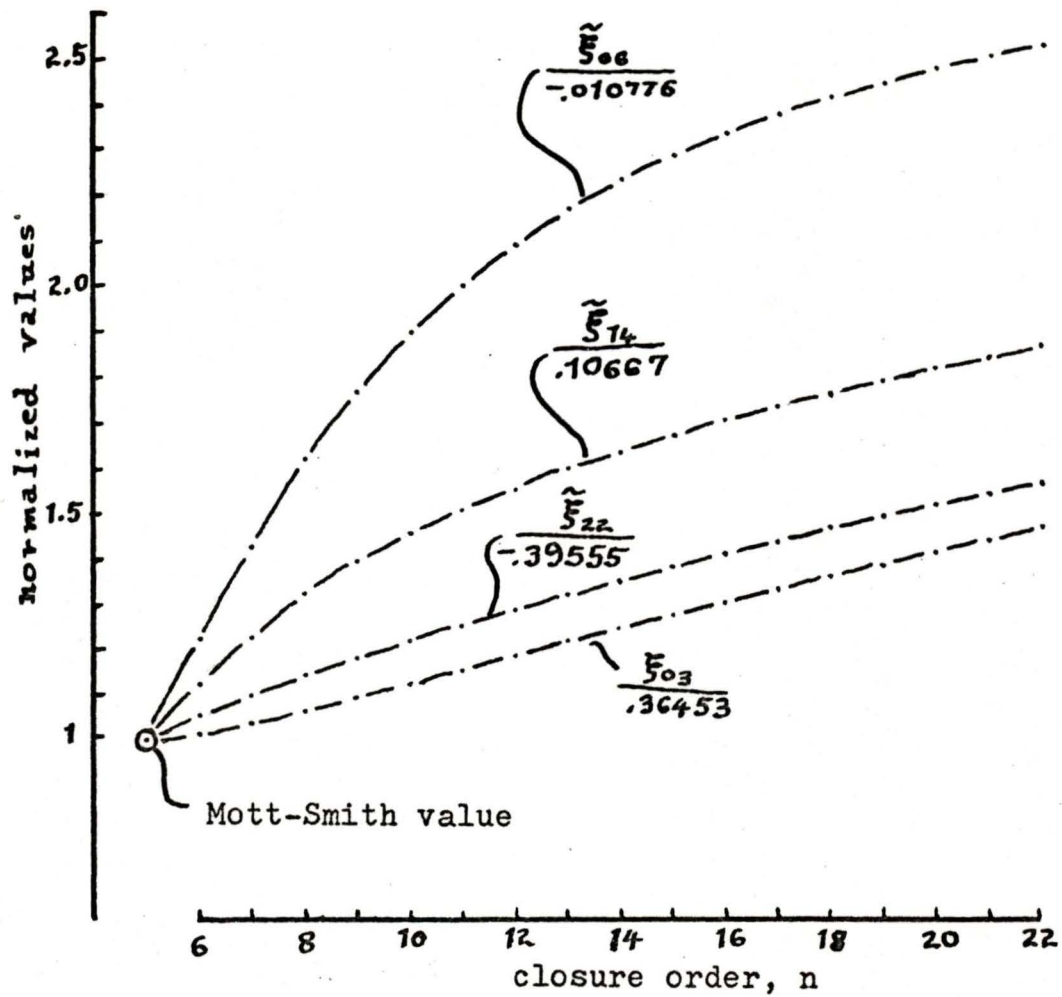


Figure 5.
Behavior of the \tilde{F}_{re} 's of order 6.

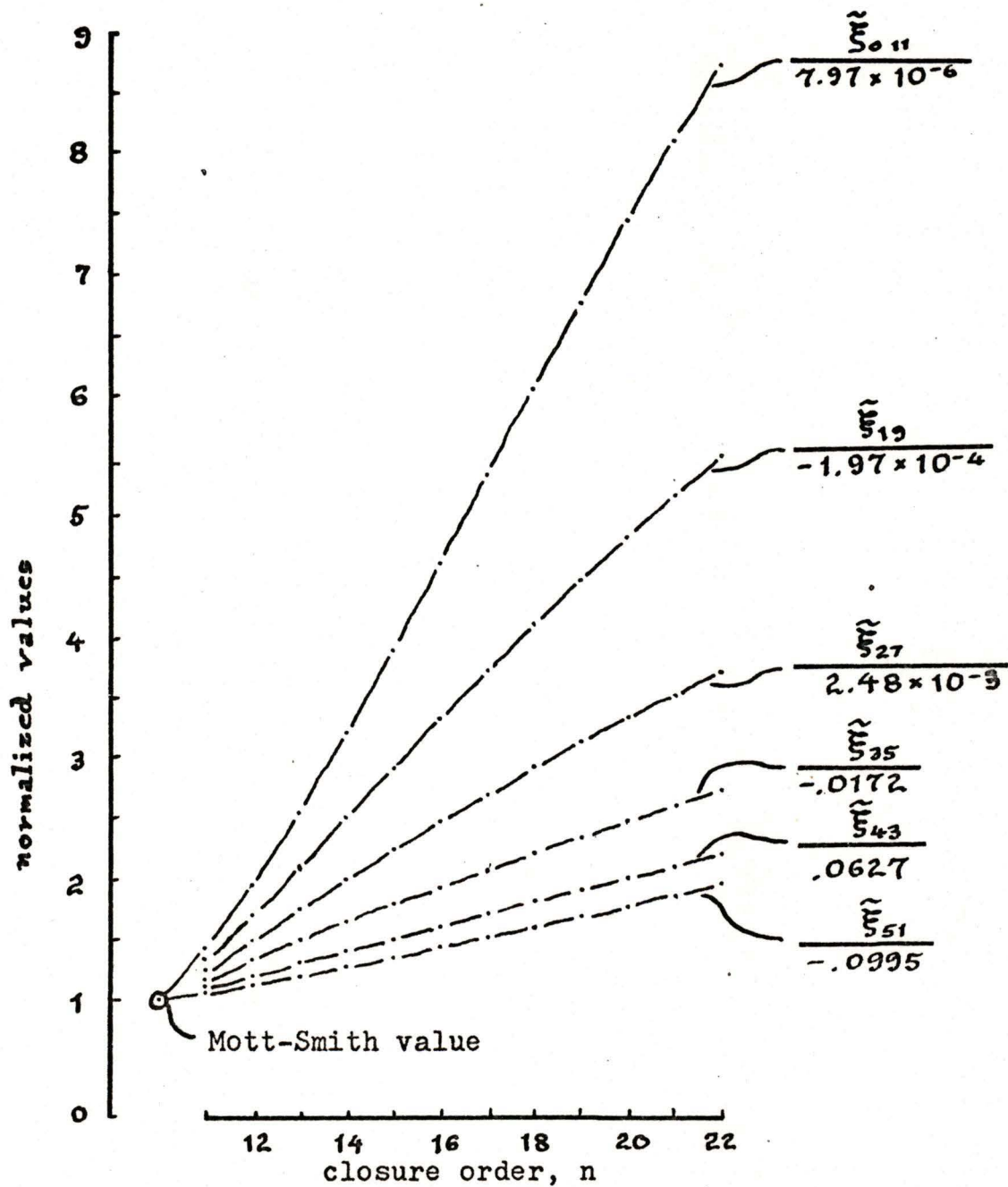
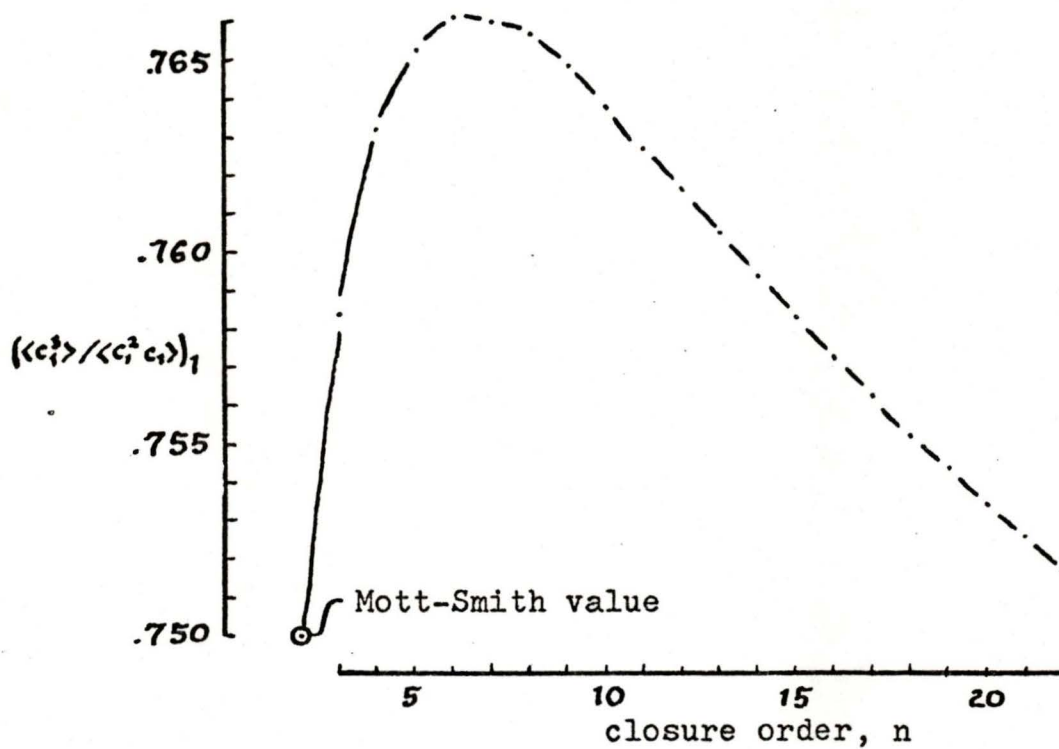
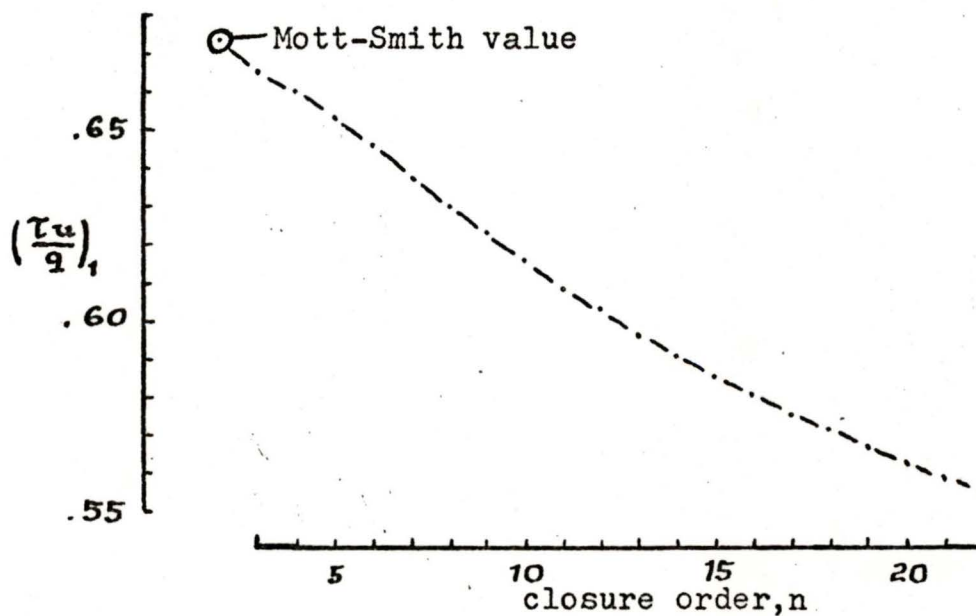


Figure 6.

Behavior of the \tilde{S}_{re} 's of order 11.

Figure 7. Behavior of $\langle c_i^2 \rangle / \langle c_i^2 c_i \rangle_1$ Figure 8. Behavior of $(\tau u / q)_1$

The similar behavior exhibited by the $\tilde{\xi}_{r,2}$'s and the fact that they all tend to vary linearly with the order of solution closure suggests that some useful information may be extracted from an apparently divergent (or optimistically slowly convergent) solution. This line of reasoning led in turn to a computational experiment, the results of which were successful, but which, in view of the ad hoc procedure used, must be regarded as still of a preliminary nature.

Specifically, consider the variable $\tilde{\xi}_{0,2}$ (chosen arbitrarily) as a single unknown parameter, and express the general $\tilde{\xi}_{r,2}$ as a linear function of $\tilde{\xi}_{0,2}$ by

$$(11.) \quad \tilde{\xi}_{r,2} = a_{r,2} \tilde{\xi}_{0,2} + c_{r,2} .$$

Given the solution $\tilde{\xi}_{r,2}$'s to any two consecutive orders of closure, equation 11 may be solved for each $a_{r,2}$ and $c_{r,2}$. Suppose that $a_{r,2}^{(n)}$ and $c_{r,2}^{(n)}$ are the values obtained from the solutions to closure orders n and $n+1$. It is found that the coefficients $a_{r,2}^{(n)}$ and $c_{r,2}^{(n)}$ converge quite rapidly as n is increased. Typical cases are shown in figures 9 and 10 where $a_{1,2}^{(n)}$ and $c_{1,2}^{(n)}$ are displayed.

We next make the hypothesis that the limit values of the various $a_{r,2}^{(n)}$ and $c_{r,2}^{(n)}$ are exact, even though they were obtained from a sequence of inexact solutions. If this be the case, then every $\tilde{\xi}_{r,2}$ can be expressed

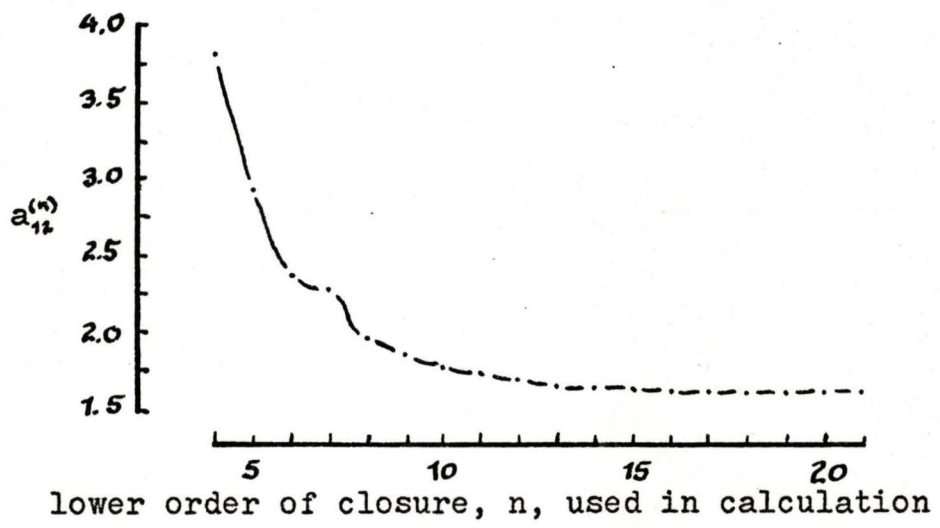


Figure 9. Convergence of $a_{12}^{(n)}$

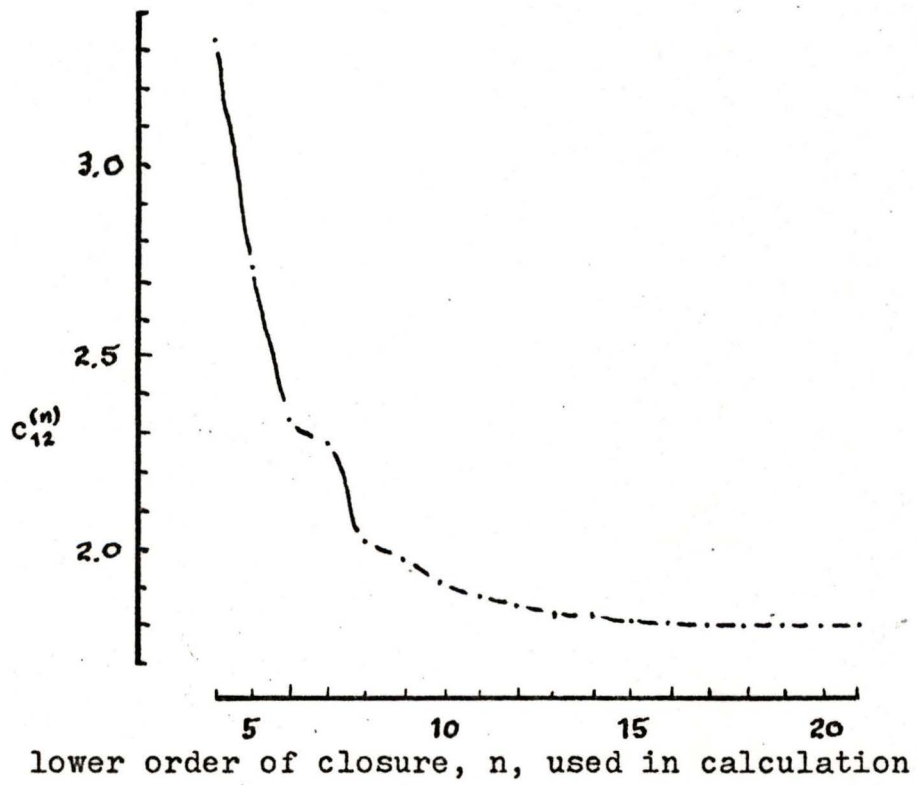


Figure 10. Convergence of $c_{12}^{(n)}$

exactly in terms of $\tilde{\xi}_{02}$ by means of equation (11). We can then return to the matrix of the fundamental equation (figure 3), pick any two equations, and solve them for $\tilde{\xi}_{02}$ and ω_1 . A necessary condition for our hypothesis to be correct is that the values obtained for $\tilde{\xi}_{02}$ and ω_1 be independent of the choice of equations, and this is indeed found to be the case.

As an example, let us display values obtained from equations $r=0, \ell=3$, and $r=0, \ell=2$. A quadratic equation for ω_1 will always be obtained and its solution in this case is $\omega_1 = .843 \pm .006$, where the second term arises from a non-zero discriminant which may be expected to vanish upon insertion of more accurate $a_{r\ell}$'s and $c_{r\ell}$'s on the physical grounds that only one solution is realizable. The accuracy may be increased by increasing the order of closure (22 was the highest used in this case). In this way the limit values of the $a_{r\ell}$'s and $c_{r\ell}$'s can be determined with greater accuracy. The solution for $\tilde{\xi}_{02}$ corresponding to the above value of ω_1 is found to be $\tilde{\xi}_{02} = -.6565 \pm .0012$. Knowing $\tilde{\xi}_{02}$ and the $a_{r\ell}$'s and $c_{r\ell}$'s we may then obtain any of the $\tilde{\xi}_{r\ell}$'s, and hence the physical variables of interest. The results for low-order quantities are as follows, where for later discussion, the values computed from f_m , are given in parentheses.

$$\left(M^{-2} \frac{u}{T} \frac{dT}{du} \right)_1 = -.9086 \quad (-.833)$$

$$\left(M^{-2} \frac{u}{P} \frac{dP}{du} \right)_1 = .7581 \quad (.833)$$

$$\left(M^{-2} \frac{1}{P} \frac{dP}{du} \right)_1 = 1.362 \quad (1.25)$$

$$\left(\frac{\tau u}{q} \right)_1 = .557 \quad (.667) \quad (\text{cf. fig. 8})$$

$$\left(\langle c_1^3 \rangle / \langle c^2 c_1 \rangle \right)_1 = .752 \quad (.75) \quad (\text{cf. fig. 7})$$

$$\left(M^{-2} \tau / \tau_0 \right)_1 = .287$$

Note that $\left(M^{-2} \tau / \tau_0 \right)_1$ is a moment of f so its value for f_{ms} is not given.

We again emphasize that the above results must be viewed as preliminary. Final justification for their use can be given only after the numerical accuracy of the entire calculation is increased, and certainly not until an adequate explanation can be given as to why the method used apparently works so well. Even with these reservations, the results are encouraging in that all the quantities listed have physically correct algebraic signs. In addition, the ratio $\left(\langle c_1^3 \rangle / \langle c^2 c_1 \rangle \right)_1$ satisfies the condition $0 < \left(\langle c_1^3 \rangle / \langle c^2 c_1 \rangle \right)_1 < 1$ proposed by Baganoff and Nathenson (1970).

An annoying question comes to mind if the above results are compared with the corresponding values based

on f_{ms} which are given in parentheses. In all cases the discrepancy is of the order of 10% or less. Why then does the solution based on f_{ms} converge so slowly (if at all)? It might be thought that a ten percent error evidenced by the low order moments in the first approximation for f could easily be corrected by just a few terms in the Hermite polynomial series.

Another interesting question can be raised with regard to the solution based on Grad's method: since the method fails for $M_1 \rightarrow \infty$, there must exist a critical finite value of the upstream Mach number above which the solution does not yield physically acceptable results to any order of closure. What is this value, and why does it exist? That the Grad solution to equation 7 for $M_1 \rightarrow \infty$ is unphysical is seen in that it requires a sub-diagonal form of the matrix, which in turn requires the relation $\xi_{r,l} \propto M_1^{-2r-l+k}$ as $M_1 \rightarrow \infty$, with $k \geq 3$.

In conclusion, it is felt that once the ad hoc method used in obtaining the final results is well understood and can be rigorously justified, the first truly nonlinear exact solution to the Boltzmann equation may be proclaimed. It is ironic that this should also be the solution of a classic problem in gas dynamics for which the degree of nonequilibrium is so strong.

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APPENDIX A

FORTTRAN PROGRAM WRITTEN TO GENERATE $\tilde{\xi}_{re}$ 'S
FROM THE MOTT-SMITH DISTRIBUTION FUNCTION

This program evaluates expression 10 to order 37, although the $\tilde{\xi}_{re}$'s are only accurate to order 23, as discussed in chapter 4. Necessary logarithms of factorials are stored in the following array

$$F(K) = \log_e(K!) .$$

Similarly, for the integer-plus-one-half factorials

$$FH(K) = \log_e((K+\frac{1}{2})!/\sqrt{\pi}) .$$

Final $(\tilde{\xi}_{re})_{m_s}$ values are stored in the array E(I) for punching on cards. Here I is an index calculated by

$$I = \left[\frac{1}{4}(2r + \ell)^2 \right] - r ,$$

where the brackets represent the largest integer less than the contained term. This is the standard ordering used in figure 2 and by many authors.

The subroutine SUM is also shown. Particulars are included at the top of the listing. Its purpose is to minimize loss of significant bits (also digits) due to the size of interim sums calculated in the adding of a column.

```

      *WATFIV
      C      MOTT-SMITH SHOCK END CONDITIONS ... TO BE USED FOR CLOSURE
      1      DOUBLE PRECISION DLOG,DEXP,L5,L2,F,FH,FA,FHA,DSQRT,T,TL,TA,TB,E,
      2      1 EEL,AK,EL,R,DABS,S,W,SL,SLH
      3      DIMENSION E(381),F(75),FH(38)
      4      DIMENSION SL(75),SLH(38)
      5      COMMON S(39,4),W,M,LU
      6      L5=DLOG(5.00)
      7      L2=DLOG(2.00)
      8      FA=0
      9      FHA=DLOG(.500)
      10     F(1)=C
      11     FH(1)=FHA
      12     DD10 K=1.37
      13     AK=K
      14     SL(K)=DLOG(AK)
      15     SLH(K)=DLOG(AK+.500)
      16     10 CONTINUE
      17     DD 15 K=38,74
      18     AK=K
      19     SL(K)=DLOG(AK)
      20     15 CONTINUE
      21     M=1
      22     DD17 I=1.76
      23     IP=I+1
      24     DD16 K=1,I
      25     16 S(K,1)=SL(K)
      26     LU=I
      27     CALL SUM
      28     17 F(IP)=W
      29     DD 19 I=1.37
      30     IP=I+1
      31     DD18 K=1,I
      32     18 S(K,1)=SLH(K)
      33     LU=I+1
      34     S(IP,1)=FH(1)
      35     CALL SUM
      36     19 FH(IP)=W
      37     C
      38     IP=1
      39     L=0
      40     IR=0
      41     I=1
      42     20 LH=L/2
      43     EL=L
      44     IRP=IR+1
      45     LRP=L+IR+1
      46     LHP=LH+1
      47     R=IR
      48     FEL=EL+.5
      49     E(I)=-(-1.00)**IR*(4.00/3.00)*DSQRT(EEL)
      50     TL=(R+EL/2.00)*L5+(-4.00*R-7.00*EL/2.00)*L2-.500*(F(IRP)+FH(LRP))
      51     T=0
      52     DD 250 KP=1,LHP
      53     K=KP-1
      54     AK=K
      55     HLMK=EL/2.0-AK
      56     HMLK=HLMK/2.0
      57     ITLMTK=2*L-2*K+1
      58     KPR=K+IR+1
      59     LMK=L-K+1
      60     LMTK=L-2*K+1
      61     IRPHL=IR+LHP
      62     61 DD 200 IQP=1,IRPHL
      63     IQ=IQP-1
      64     Q=IQ-LH
      65     O=Q+EL/2.0
      66     ITQ=O*2.0+1.0
      67     TB=0
      68     FA=EL/2.0-AK-Q
      69     IAJ=DABS(FA)+1
      70     IN=Q+HLMK+1
      71     TD=-HMLK+Q/2.0
      72     IND=2.0*R+EL/2.0+AK-Q+1.0
      73     IM=0

```

```

73      DO 70 J=IAJ,IND,2
74      JM=JM+1
75      AJ=J-1
76      NUM=AJ*TN
77      IDN1=AJ/2.0+TD+1.0
78      IDN2=AJ/2.0-TD+1.0
79      IF(NUM*IDN1*IDN2*ITQ) 30,30.50
80      30 WRITE(6,40) NUM,IDN1,IDN2,ITQ,K,TD,0,AJ
81      40 FORMAT( 5(2X,I3),3(3X,F9.2))
82      50 CONTINUE
83      S(1,4)=F(NUM)
84      S(2,4)=-F(IDN1)
85      S(3,4)=-F(IDN2)
86      S(4,4)=-F(ITQ)
87      S(5,4)=-AJ*L2
88      LU=5
89      M=4
90      CALL SUM
91      FHA=W
92      IF(FHA+16.D1) 55,55,60
93      55 S(JM,3)=0
94      GO TO 70
95      60 S(JM,3)=DEXP(FHA)
96      70 CONTINUE
C
97      M=3
98      LU=JM
99      CALL SUM
100     S(ITQ,2)=3.00**Q*W
101     200 CONTINUE
102     S(1,4)=F(ITLMTK)
103     S(2,4)=F(KPR)
104     S(3,4)=-F(KP)
105     S(4,4)=-F(LMK)
106     S(5,4)=-F(LMTK)
107     S(6,4)=TL
108     M=4
109     LU=6
110     CALL SUM
111     FHA=W
112     LU=IRPHL
113     M=2
114     CALL SUM
115     S(KP,1)=(-2.00)**K*W*DEXP(FHA)
116     250 CONTINUE
117     LU=LHP
118     M=1
119     CALL SUM
120     E(1)=E(1)*W
121     IF(IP-4) 280,260,280
122     260 KP=I-IP+1
123     WRITE(6,270)(E(K),K=KP,1),L,IR

124     270 FORMAT(4(2X,D18.11),2(3X,I3))
125     WRITE(7,470)(E(K),K=KP,1)
126     470 FORMAT(4(2X,D18.11))
127     IF(I-16) 8100,8020,8100
128     8020 IF(DABS(E(8)-.602700)-1.D-3) 8100,8100,8800
129     8100 CONTINUE
130     IP=1
131     GO TO 290
132     280 IP=IP+1
133     290 CONTINUE
C
134     INDEX INCREMENT
135     IF(IR) 350,350,300
136     300 IR=IR-1
137     L=L+2
138     I=I+1
139     GO TO 20
140     350 IF(I-37) 370,400,400
141     370 IR=(L+1)/2
142     L=1+2*LH-L
143     I=I+1
144     GO TO 20
145     400 KP=I-IP+1
146     WRITE(6,270)(E(K),K=KP,1)
147     8800 CONTINUE
148     STOP
149     END

```

```

150      SUBROUTINE SUM
      C      THE BEST POSSIBLE SUM ROUTINE FOR BINARY MACHINE & FLOATING POINT
      C      SUM OF THE FIRST LU NUMBERS OF S(K,J) IS LEFT IN TSMAL, J SELECTS
      C      WHICH COLUMN TO ADD.
151      C      FIRST ARRANGE IN ASCENDING MAGNITUDE
152      DOUBLE PRECISION S,TSMAL,DABS,
153      DOUBLE PRECISION TMP
154      COMMON S(39,4),TSMAL,J,LU
155      ICF=1
156      LUM=LU-1
      LUMM=LU-2
      C      HANDLE THE TRIVIAL CASES-NO CHOICE OF ADDITION ORDER
157      DO 9020 K=1,LUM
158      9020 TSMAL=S(1,J)
159      GO TO 9401
160      9030 TSMAL = S(1,J)+S(2,J)
161      GO TO 9401
162      9035 CONTINUE
      C      BACK TO WORK- ORDER TERMS BY MAGNITUDE
163      DO 9100 K=1,LUM
164      IS=K
165      KP=K+1
166      TSMAL=S(K,J)
167      DO 9060 I=KP,LU
168      IF(DABS(S(I,J))-DABS(TSMAL)) 9040,9060,9060
169      9040 TSMAL=S(I,J)
170      IS=I
171      9060 CONTINUE
172      S(IS,J)=S(K,J)
173      S(K,J)=TSMAL
174      9100 CONTINUE
      C      ALTERNATE ENTRY HERE IF TERMS ARE ALREADY ASCENDING ORDERED
175      9101 CONTINUE
176      DO 9400 K=1,LUMM
177      KP=K+1
178      KPP=K+2
179      IF(ICF.EQ.0) GO TO 9105
180      C      JCS=-1
181      DO 9900 JC=KP,LU
182      IF(S(JC,J).GT.(2.D0*S(K,J))) GO TO 9910
183      IF(S(JC,J)*S(K,J).GT.0.D0) GO TO 9900
184      JCS=JC
185      9900 CONTINUE
186      ICF=0
187      9910 IF(JCS.LT.0) GO TO 9105
188      TMP=S(JCS,J)
189      JTP=JCS-K
190      IF(JTP.EQ.0) GO TO 9105
191      DO 9950 JC=1,JTP
192      JJC=JCS-JC
193      JCP=JJC+1
194      9950 S(JCP,J)=S(JJC,J)
195      S(KP,J)=TMP
196      C      9105 CONTINUE
197      TSMAL=S(K,J)+S(KP,J)
198      DO 9200 I=KPP,LU
199      IM=I-1
200      IF(DABS(S(I,J))-DABS(TSMAL)) 9110,9150,9150
201      9110 S(IM,J)=S(I,J)
202      IF(I=LU) 9200,9120,9200
203      9120 S(I,J)=TSMAL
204      GO TO 9200
205      9150 S(IM,J)=TSMAL
206      GO TO 9400
207      9200 CONTINUE
208      9400 CONTINUE
209      TSMAL= S(KPP,J) +S(KP,J)
210      9401 CONTINUE
211      RETURN
212      END

```

APPENDIX B
 FORTRAN PROGRAM WRITTEN TO SOLVE THE
 FUNDAMENTAL EQUATION SYSTEM

This program solves the upper-triangular form of equation 7 ($M_1 \rightarrow \infty$) for the unknown $\tilde{F}_{r\ell}$'s and $\omega_1 / (1.25A_2)$ (cf. figure 3). It reads the $(\tilde{F}_{r\ell})_{m_5}$ values needed for closure into the array E(I), where the index, I, is discussed in appendix A. The eigenvalues were taken directly from Alterman et al. (1962) and placed on two separate decks for checking purposes. In this program they are placed into the array EL(I). Terms "1" and "4" are stored in arrays T1(I) and T4(I), where I is the equation index. A Newton - Raphson method is used to determine ω_1 . The variable W(JRC) is used to store $\omega_1 / (1.25A_2)$, where JRC is the order of closure. Equation $r=0, \ell=1$ is to be satisfied by the Newton-Raphson method. The error in satisfying this equation is stored in DE as defined on line 74 of the listing. The final results, the unknown $\tilde{F}_{r\ell}$'s are stored in array EF(I), from which other variables of interest are calculated.

```

1 C SOLVE FOR SHOCK END CONDITIONS UPSTREAM FOR LARGE M
2 DIMENSION EF(380),IDL(379),EL(361),IF(380),E(380),T1(361),T4(361),
3 W(39),ID(379)
4 DOUBLE PRECISION EL,E,EF,BT,W,R2,ELL,R,T1,T4,WF,WN,DSORT,DABS,
5 DF,DEF,DFR,R3,R56,C56
6 READ(5,20)(ID(I),IDL(I),I=1,379)
7 FORMAT(7(12,11,1X))
8 C56=5.00/6.00
9 R56=DSORT(C56)
10 R3=DSORT(3.00)
11 TDC=9.00/(1.250)*15.00
12 IR=0
13 L=0
14 DO80 I=1,379
15 IF(ID(I)-800000000) 50,50,40
16 IF=(ID(I)-900000000)/1000000
17 L=0
18 GO TO 80
19 J=(2*IR+L+2)*(2*IR+L+2)/4-IR
20 L=L+1
21 EL(J)=ID(I)
22 ELL=IDL(I)
23 EL(J)=-EL(J)/1.09-ELL/1.09
24 CONTINUE
25 R2=DSORT(2.00)
26 JOTP=36
27 C JOTP IS HIGHEST ORDER CONSIDERED, NOW READ CLOSURE TERMS
28 READ(5,100)(E(J),J=1,380)
29 FORMAT(4(2X,D18.11))
30 C FIND OFF DIAGONAL ELEPHANTS
31 JRR=1
32 R=0
33 ELL=1.00
34 I=2
35 CONTINUE
36 TA(I)=0.00
37 IF(FLL)140,160,140
38 TA(I)=EL+DSORT((R+1.00)/((2.00*ELL-1.00)*(2.00*FLL+1.00)))
39 T1(I)=-((FLL+1.00)*DSORT((R+ELL+1.500)/((2.00*ELL+1.00)*(2.00*FLL
40 +3.00)))
41 I=I+1
42 IF(R) 180,200,180
43 R=R-1.00
44 ELL=FLL+2.00
45 GO TO 120
46 CONTINUE
47 JRR=JRR+1
48 IF(JRR-JOTP-1) 220,240,240
49 R=JRR/2
50 ELL=-2*(JRR/2)+JRR
51 GO TO 120
52 CONTINUE
53 WTR=1.D-3
54 W(3)=.53500
55 JRC=3
56 C TO SOLVE FOR ONE COMPLETE ANSWER SET AT ORDER JRC
57 ITOP=(JRC+3)*(JRC+3)/4
58 IBOT=(JRC+2)*(JRC+2)/4+1
59 ITSA=IBOT-1
60 IBSA=(JRC+1)*(JRC+1)/4+1
61 DO 300 I=IBOT,ITOP
62 EF(I)=E(I)*(-1.00)**(JRC+1)
63 ISF=1
64 C ATTEMPT MATRIX SOLVE WITH GUESSED W
65 JRR=JRC
66 IBOT=IBSA
67 ITOP=ITSA
68 IBS=(JRR+1)/2+1
69 DO 300 IT=IBOT,ITOP
70 I=IT+IBS
71 IM=I-1
72 IF(T4(IT)) 294,287,294
73 BT=T1(IT)*EF(I)
74 GO TO 300
75 BT=T1(IT)*EF(I)+T4(IT)*EF(IM)
76 EF(IT)=-BT/((W(JRC)*E_(IT)-1)*R56)
77 IF(JRR-2) 320,340,320
78 JRR=JRR-1
79 ITOP=IBOT-1
80 IBOT=(JRR+1)*(JRR+1)/4+1
81 GO TO 280

```

```

C      CLOSURE VERIFICATION (W GUESS CORRECT)
74     340 DE=-R2+C56+T4(2)+EF(3)+T1(2)*EF(4)
75     IF (ISF-1) 300,360,360
76     360 WF=W(JRC)
77     W(JRC)=W(JRC)+WTR
78     DEF=DE
79     ISF=0
80     GO TO 270
81     400 CONTINUE
82     IF (DABS(DE)-1.D-11)420,440,440
83     420 IF (DABS(W(JRC)-WF)-1.0-11)480,440,440
84     440 WN=W(JRC)-(W(JRC)-WF)*DE/(DE-DEF)
85     WF=W(JRC)
86     W(JRC)=WN
87     DEF=DE
88     GO TO 270
C      SUCCESSFUL GUESS AT W. COMPLETE SOLUTION FOR ORDER JRC SITS IN EF
89     480 CONTINUE
90     WRITE(6,50)JRC,W(JRC),(EF(J),J=3,10)
91     500 FORMAT(' ORDER #',I2,' W = ',D18.11,'/,4(2X,D18.11),/,4(2X,D18.11)
92     1 ,/)
93     EF(3)=-P2*EF(3)/R3
94     EF(4)=-2.D0*EF(4)/R3
95     EF(5)=-R3*EF(5)/R2
96     EF(5)=5.D0*(EF(6)+EF(5))/5.D0
97     EF(1)=.500*EF(6)/EF(5)
98     EF(2)=W(JRC)*TOC*EF(4)
99     505 WRITE(6,505)(EF(J),J=1,2)
100    505 FORMAT(' S(111)/S(1) = ',E13.6,' TAU/TAU(0) = ',E13.6,'/,40X,
101    1 'GRADIENTS')
102    WRITE(6,506)(EF(J),J=3,5)
103    506 FORMAT(' TEMP = ',E13.6,' TAU = ',E13.6,' Q = ',
104    2 'E13.6,' S(111) = ',E13.6)
105    WRITE(6,508)
106    508 FORMAT(1X,100(' '),/)
107    IF (JRC-JOT) 510,2000,2000
108    510 JRM1=JRC
109    JRM2=JRC-1
110    JRM3=JRC-2
111    JRC=JRC+1
112    IF (JRC-5) 520,540,560
113    520 W(JRC)=W(JRM1)
114    GO TO 250
115    540 WTR=.500*(W(JRM1)-W(JRM2))
116    GO TO 580
117    560 WTR=W(JRM1)-2.D0*W(JRM2)+W(JRM3)
118
119    580 W(JRC)=2.D0*W(JRM1)-W(JRM2)
120    IF (DABS(WTR)-1.D-8) 600,250,250
121    600 WTR=2.D-8
122    GO TO 250
123    2000 CONTINUE
124    STOP
125    END

```

Sample Output

```

ORDER # 3 W = 0.464578239900 00
0.102202245390 01 -0.720696655310 00 -0.102202245390 01 0.330522170670 00
-0.641862372080 00 0.602747450790 00 -0.114363289800 00 UUJUUUUUUUUUUUUUUUU
S(111)/S(1) = 0.7584330 00 TAU/TAU(0) = 0.1740150 00
GRADIENTS
TEMP = -0.8344730 00 TAU = 0.8321890 00 Q = 0.1251720 01 S(111) = 0.1898690 01
*****

ORDER # 4 W = 0.502824726830 00
0.102524273370 01 -0.718419583550 00 -0.102524273370 01 0.341789618380 00
-0.638289788930 00 0.62415725430 00 -0.127872948550 00 0.647953520350 00
S(111)/S(1) = 0.7533190 00 TAU/TAU(0) = 0.1877050 00
GRADIENTS
TEMP = -0.8371070 00 TAU = 0.8295590 00 Q = 0.1255660 01 S(111) = 0.1916940 01
*****

ORDER # 5 W = 0.537264077540 00
0.103088591610 01 -0.714429251030 00 -0.103088591610 01 0.347325144980 00
-0.643688382570 00 0.639418290880 00 -0.137452832580 00 0.660928071690 00
S(111)/S(1) = 0.7553410 00 TAU/TAU(0) = 0.1994480 00
GRADIENTS
TEMP = -0.8417150 00 TAU = 0.8249520 00 Q = 0.1262570 01 S(111) = 0.1932600 01

```

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